

## Architecture= Constraints

System-level

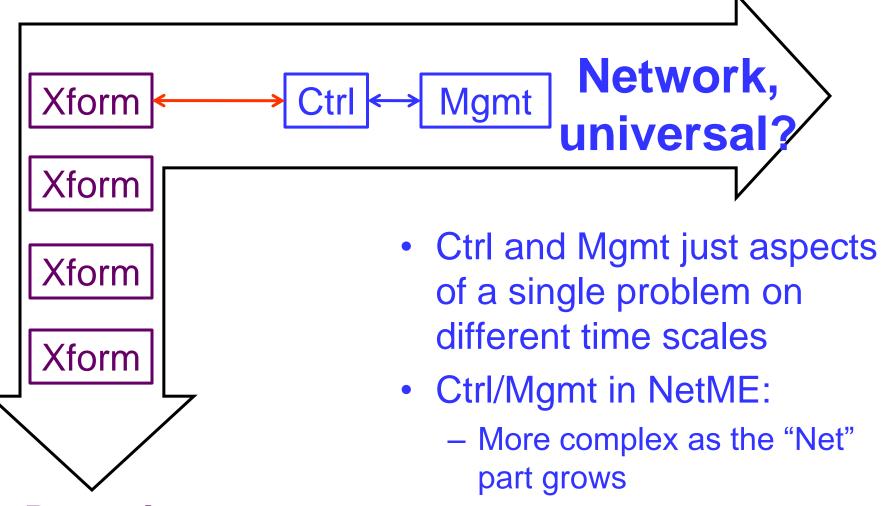


Aim: a universal taxonomy of complex systems and theories

**Protocols** 

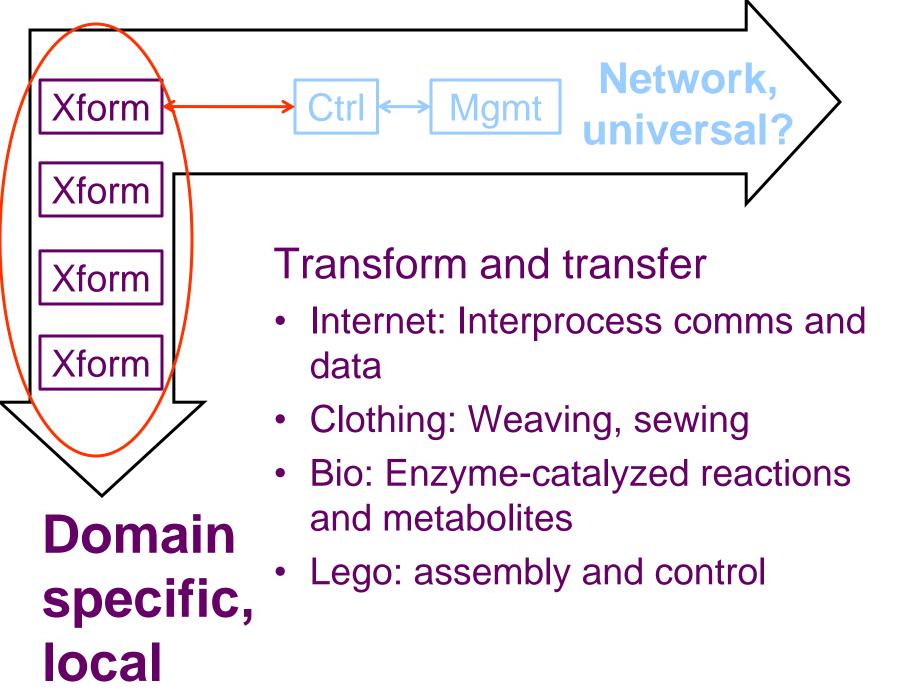
Component

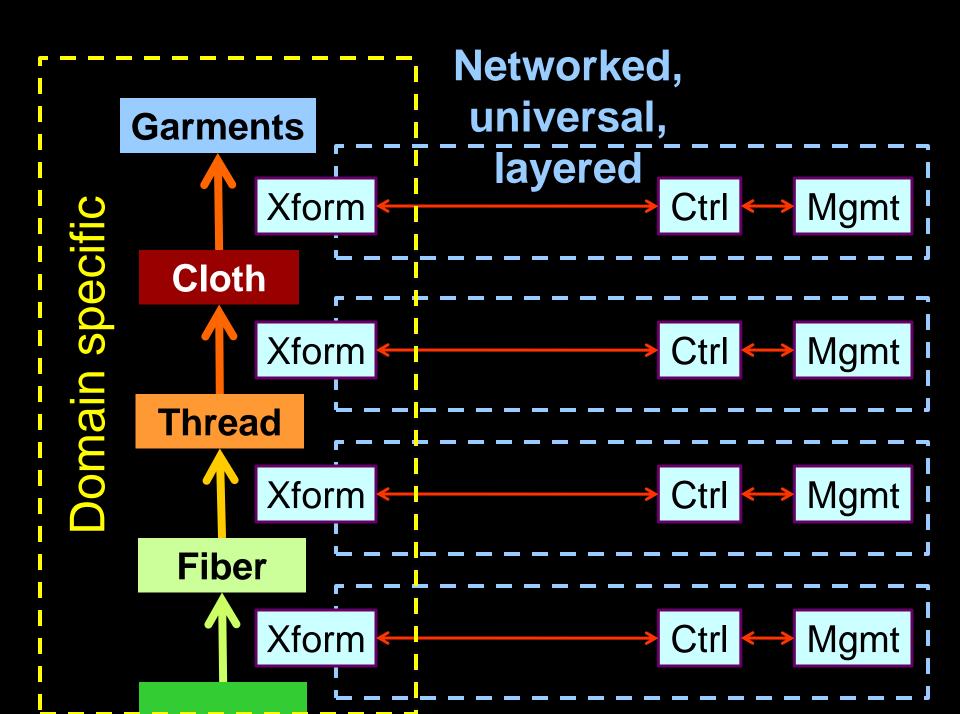
- Describe systems/components in terms of constraints on what is possible
- Decompose constraints into component, systemlevel, protocols, and emergent
- Not necessarily unique, but hopefully illuminating nonetheless

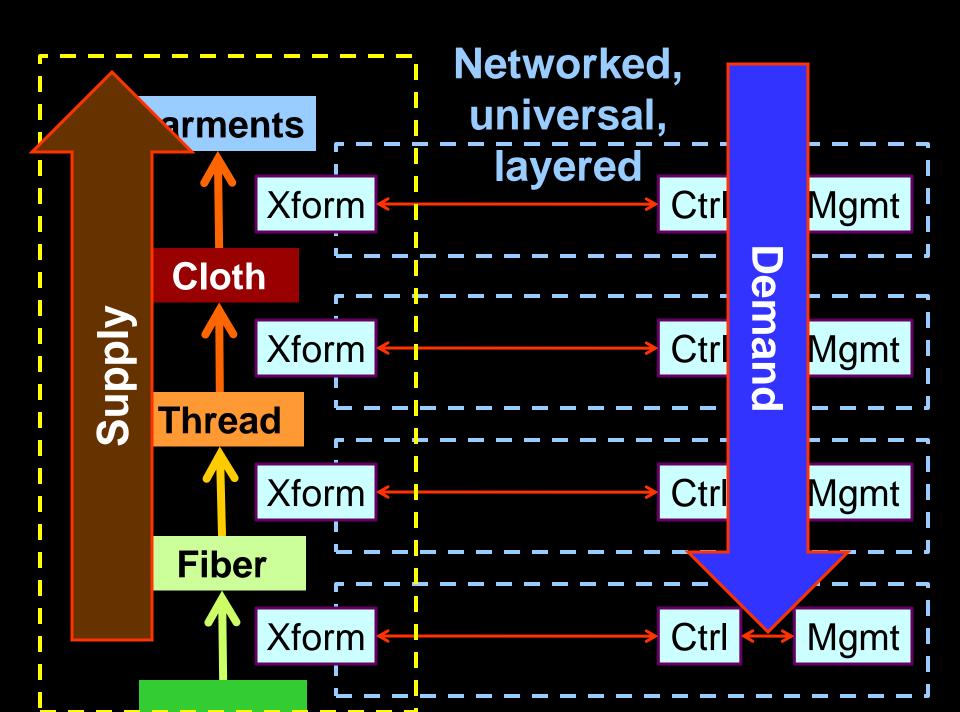


Domain specific, local

- Will be our focus/goal of a unified theory
- From physics to information to computation to control







#### **Universal strategies?**

Even though garments seem analog/continuous

Garments

Garments have limited access to threads and fibers

quantization for robustness

Cloth

Xform

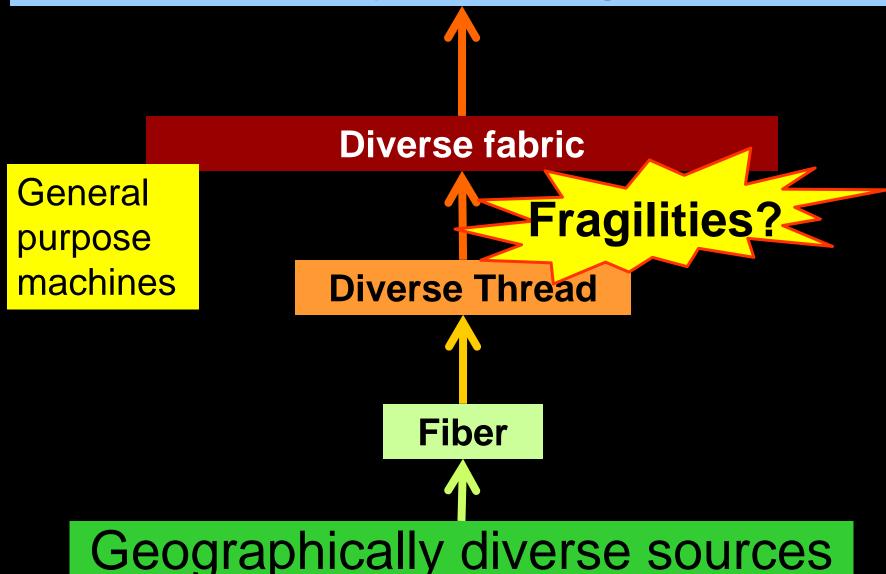
Xform

Fiber

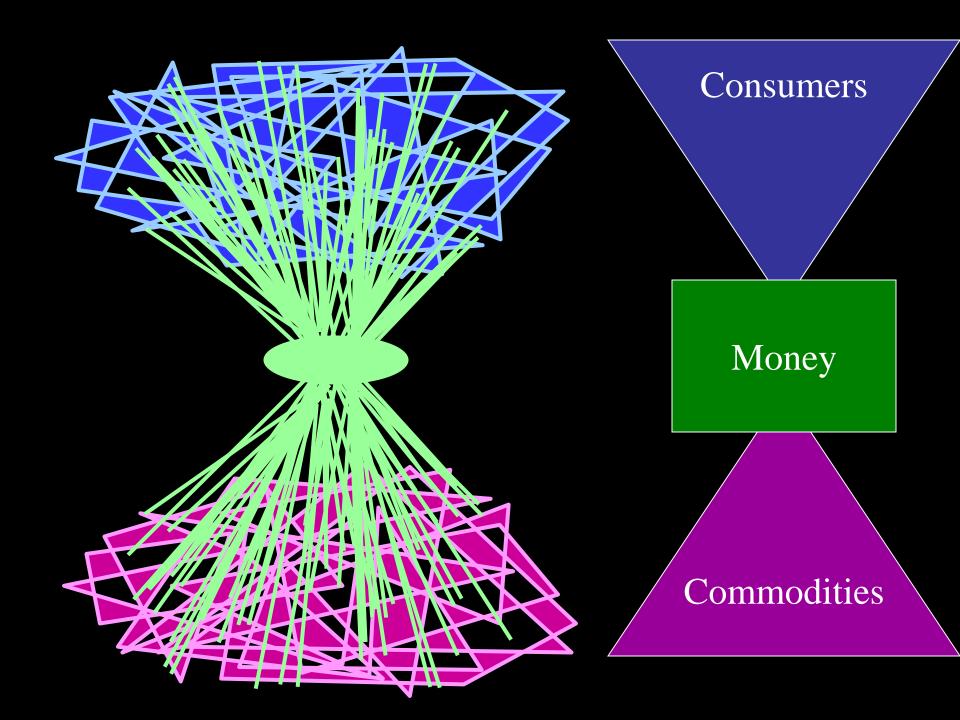
constraints on cross-layer interactions

Prevents unraveling of lower layers

### Functionally diverse garments

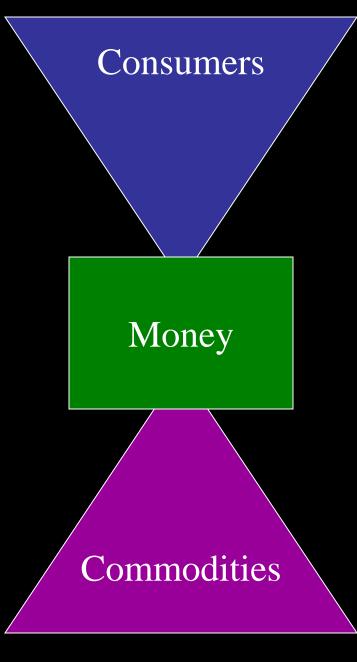


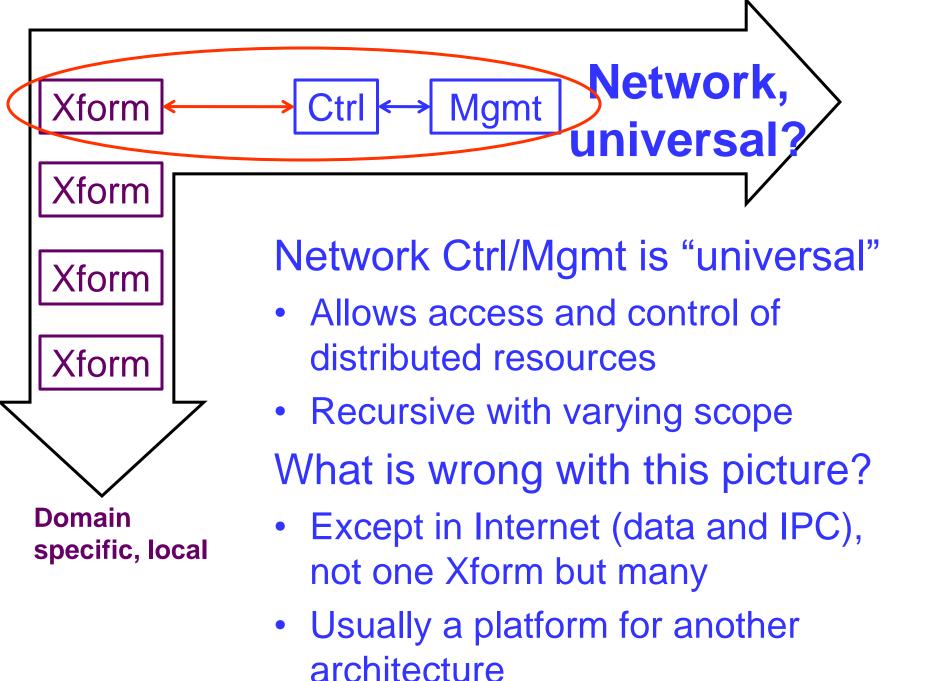
### Money



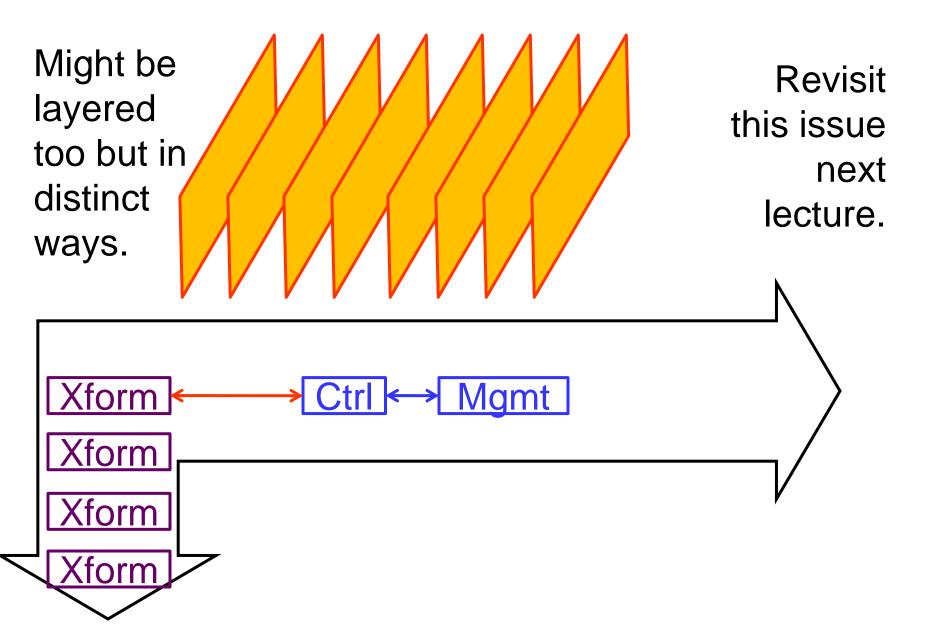
### New fragilities

- Theft, counterfeiting, fraud, and "creative accounting" are now possible
- The beginning of a growing complexity-fragility spiral
- Complex legal infrastructure
- Law, banking, finance, Ponzi schemes, derivatives, credit default swaps, ...

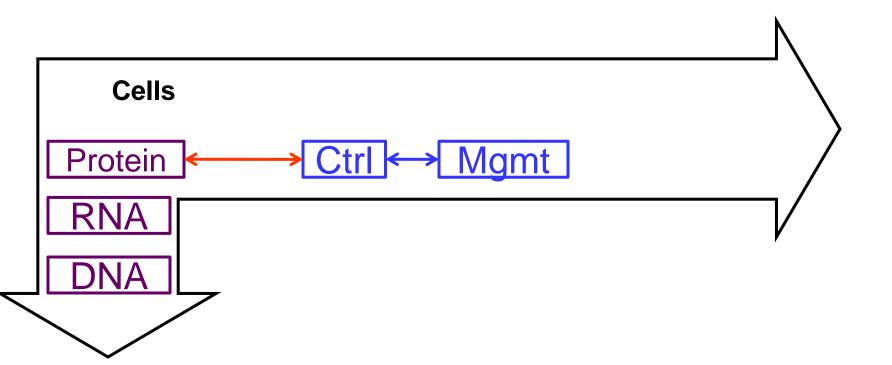




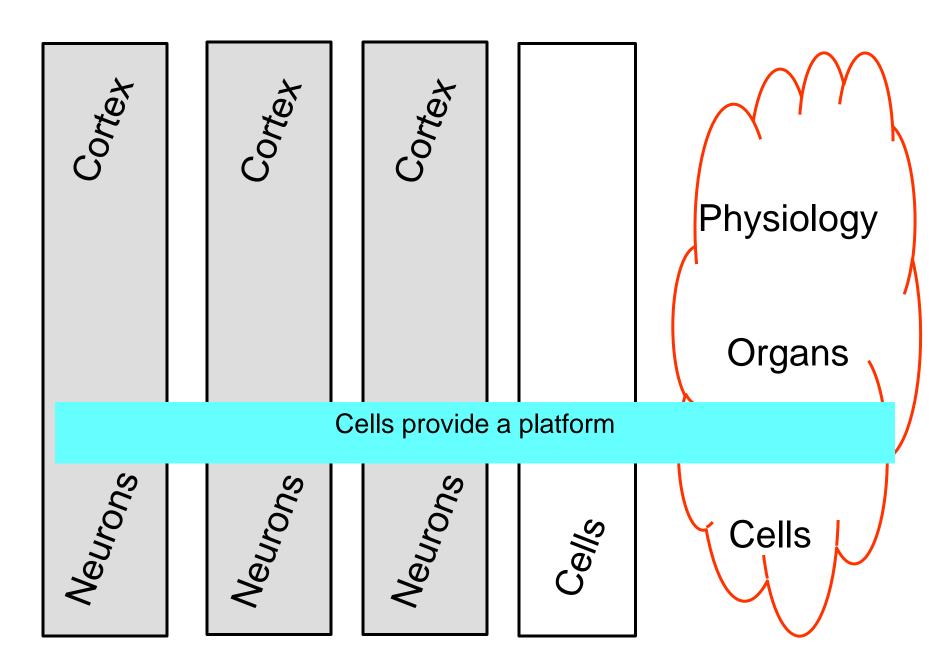
#### Usually a platform for other architectures



For example, cells have internal layering that provides a platform, for a completely separate layering at the organ level



#### Layering of neural control



Meta-layers Cortex Physiology Prediction Goals **Actions Actions** errors







Diverse toys

control



Universal Control

assembly



Diverse instructions





#### Robust yet fragile

#### Extremes of

- Robust yet fragile
- Simplicity and complexity
- Constrained and flexible
- Frozen and evolvable
- Digital and analog
- Diverse and conserved

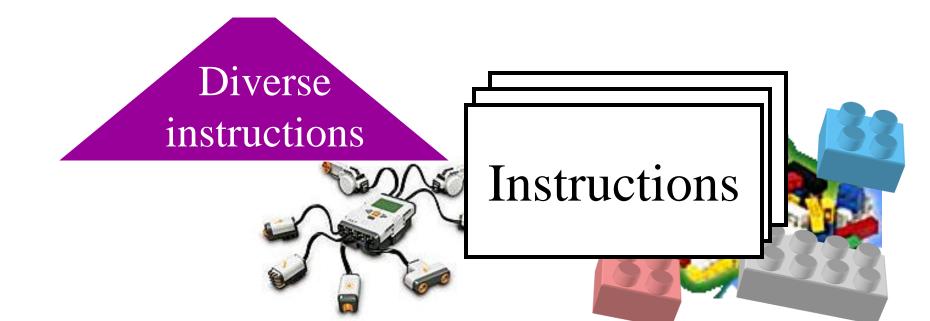


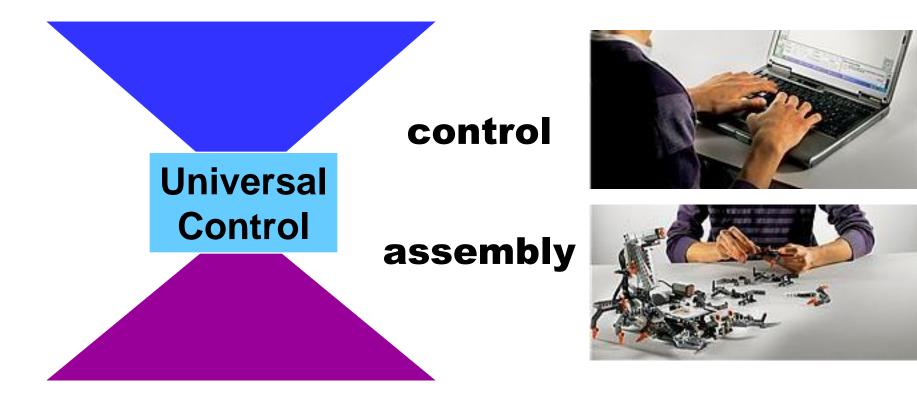






Diverse toys





**Huge variety** 







Standardized mechanisms
Highly conserved

control



assembly



**Huge variety** 



Lego

**Huge variety** 

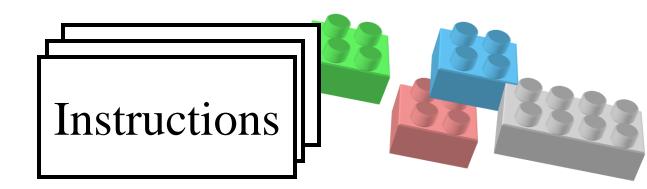
Limited environmental uncertainty needs minimal control



## Standard assembly



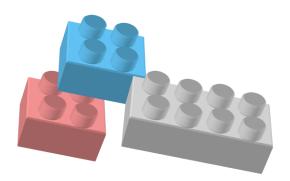
**Huge variety** 



# Diverse toys

## Standard assembly

Diverse instructions



Question: what is the difference between hourglass and bowtie here?





A "minimal" setting to address this issue.

Variety of bricks

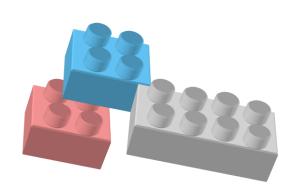
Snap

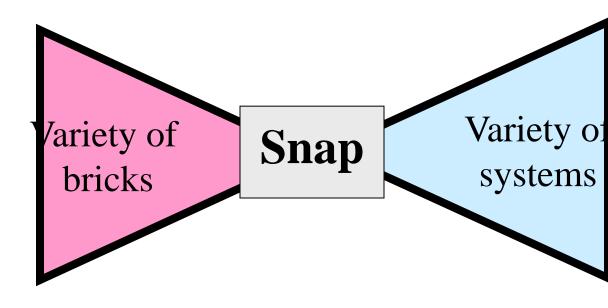
Variety of systems

The snap is a static interface specification.





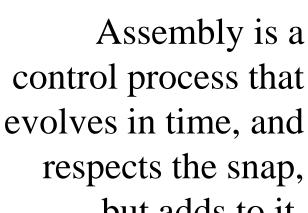


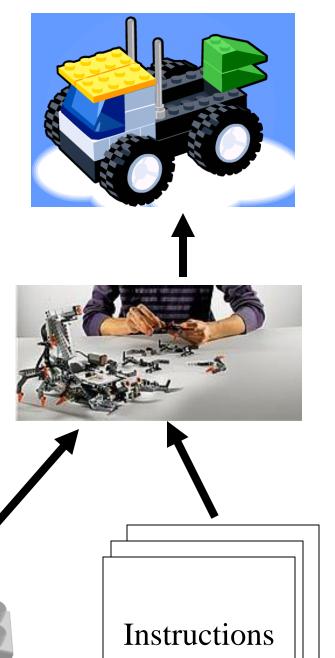


### Diverse toys

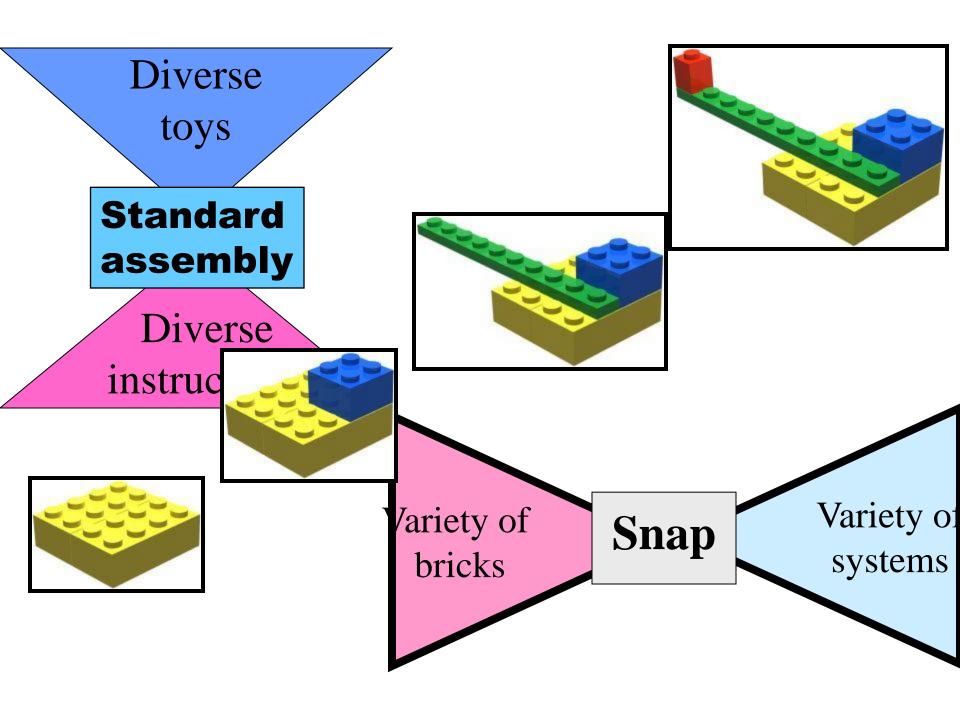
#### **Standard** assembly

Diverse instructions but adds to it.

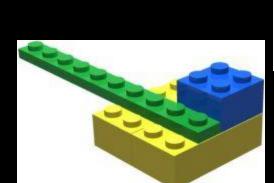


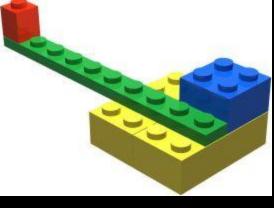


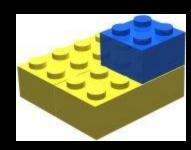
It inputs instructions and components and outputs assembled systems.

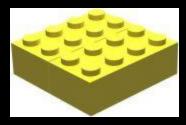


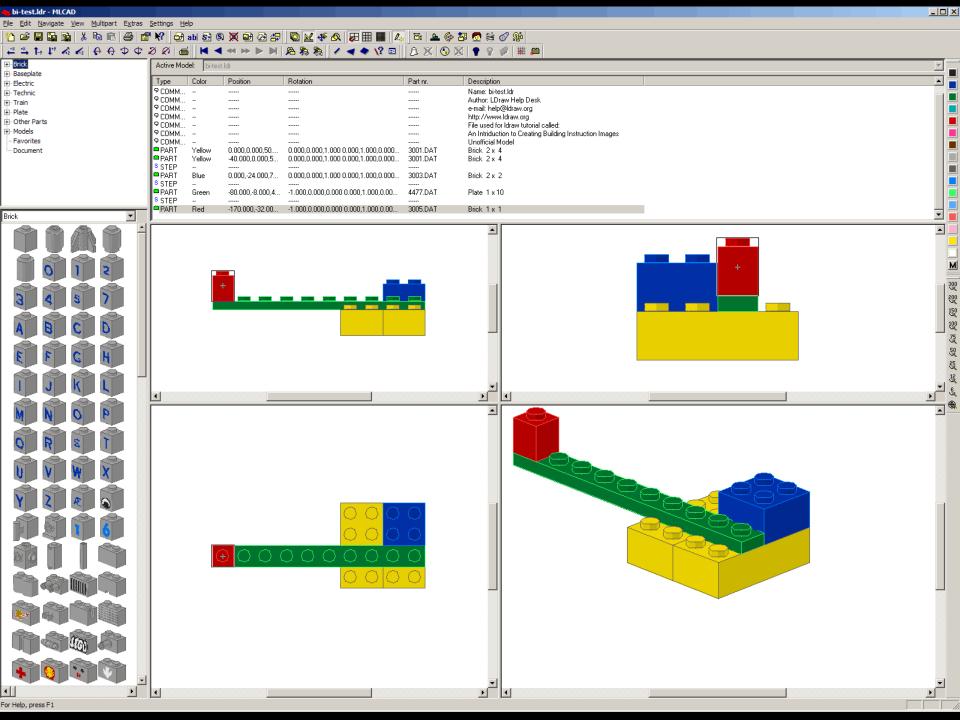
# Computer aided design tools

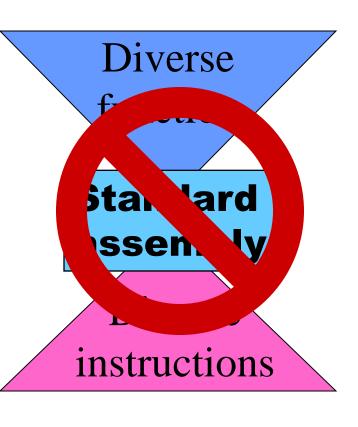




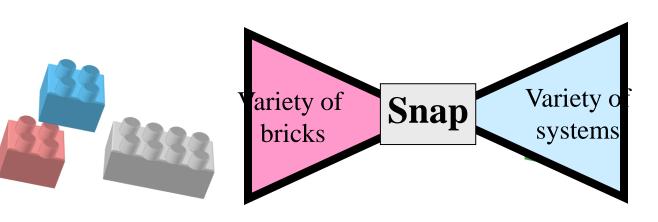


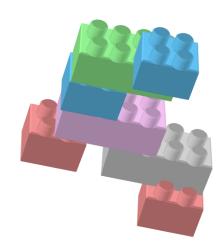






Random, uncontrolled, snap connection of Lego parts yields "nonfunctional" toys.





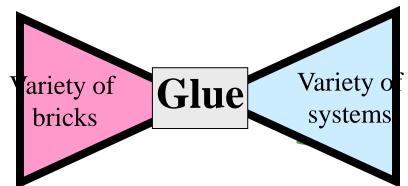
# Diverse function

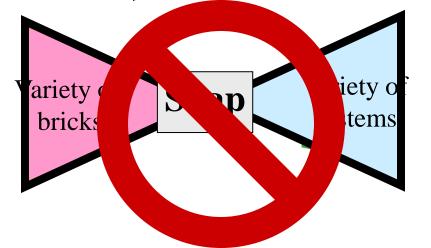


# Standard assembly

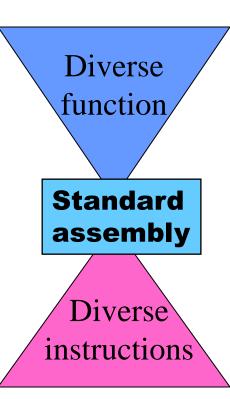
Loss of reuse, gain in robustness.

Diverse instructions





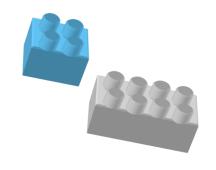


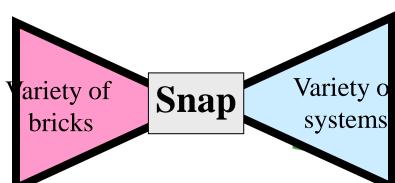


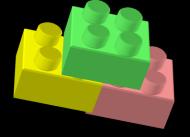
### Robustness/ Evolvability



- A huge variety of new and different toys can be built
- From a huge variety of different components
- Both toys and components can be rearranged and added in new ways
- Yet fragile?







### Yet fragile

- Add or remove a tiny, indistinguishable amount of material from either side of a key interface.
- $\rightarrow$  Complete failure.
- Other parts of the bricks may be nicked or cut with minimal impact
- This robust, yet fragile (RYF) feature of protocols is a candidate for a universal law
- "Layering" hides the snap in an assembly
- What robustness/fragility properties do alternative protocols have?

### Lego system requirements

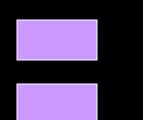
	Alternative designs?			
Performance				
Trauma				
Allowed connections				
Reuse				
Evolvable parts				
Evolvable systems				
Labor cost				
Parts cost				



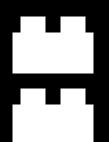


Consider some alternative interfaces and their tradeoffs...





No interface. Simple blocks.



Standard interface. (Wild type.)



Add glue to hold the parts together.



Injection mold the whole toy from scratch.



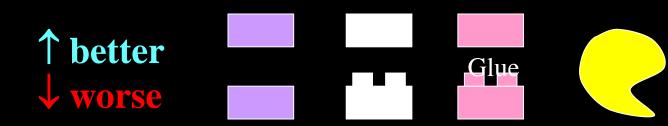






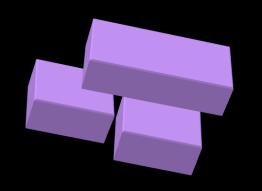
	Smooth	WT	Glue	Mold
Performance	<b>\</b>			<b>↑</b> ↑
Trauma	<b>1</b>		<b>↑</b>	<b>↑</b> ↑
Allowed connections	$\uparrow \uparrow$			<b>\</b>
Reuse			<b>1</b>	<b>↓</b> ↓
Evolvable parts	<b>\</b>			<b>+</b>
Evolvable systems	<b>↓</b> ↓			<b>+</b>
Labor cost	<b>\</b>		<b>\</b>	<b>1</b>
Parts cost	<b>↑</b>		<b>\</b>	<b>↑</b>

- Lego is "optimally robust" (Pareto) not "optimal."
- Similar to complex engineering systems and biology.

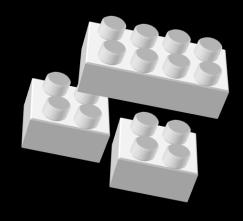


	Smooth	WT	Glue	Mold
Performance	<b>\</b>			<b>↑</b> ↑
Trauma	<b>↓</b> ↓		<b>↑</b>	$\uparrow \uparrow$
Allowed connections	<b>^</b>			<b>↓</b> ↓
Reuse			<b>↓</b> ↓	$\downarrow\downarrow$
Evolvable parts	<b>\</b>			<b>\</b>
Evolvable systems	<b>↓</b> ↓			<b>\</b>
Labor cost	<b>\</b>		<b>\</b>	<del> </del>
Parts cost	<b>↑</b>		<b>\</b>	<b>↑</b>

# Fragility: Perturbing the snap connector?



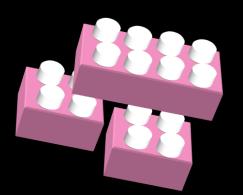
Smooth is robust



WT is *very* fragile

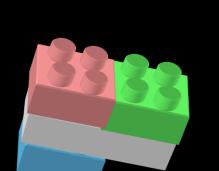


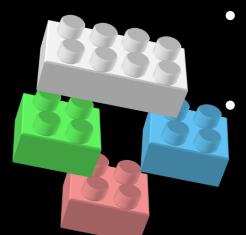
No connections, no fragility



Glued is less fragile



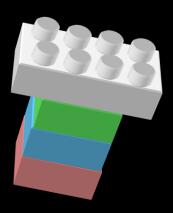


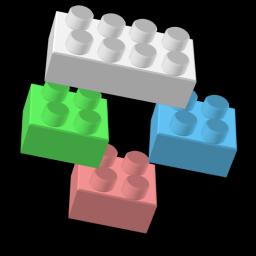


# Robust or fine-tuned?

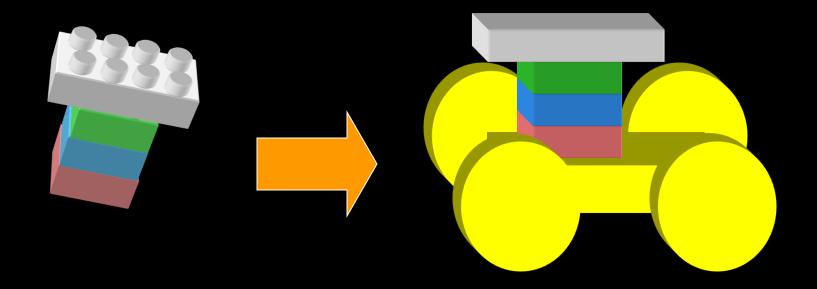
- Set of all possible interconnections is a (combinatorial) huge set.
- Set of interesting toys is also large, but an infinitesimally small subset. Very special and finely tuned.
- Similarly, among the potential toy *systems* architectures using the same plastic material, Lego is highly structured and finely tuned.
- At the component level, the stud-and-tube coupling is very finely machined.
- Robust yet fragile (RYF) is universal in complex engineering and biology

# The evolution of complexity



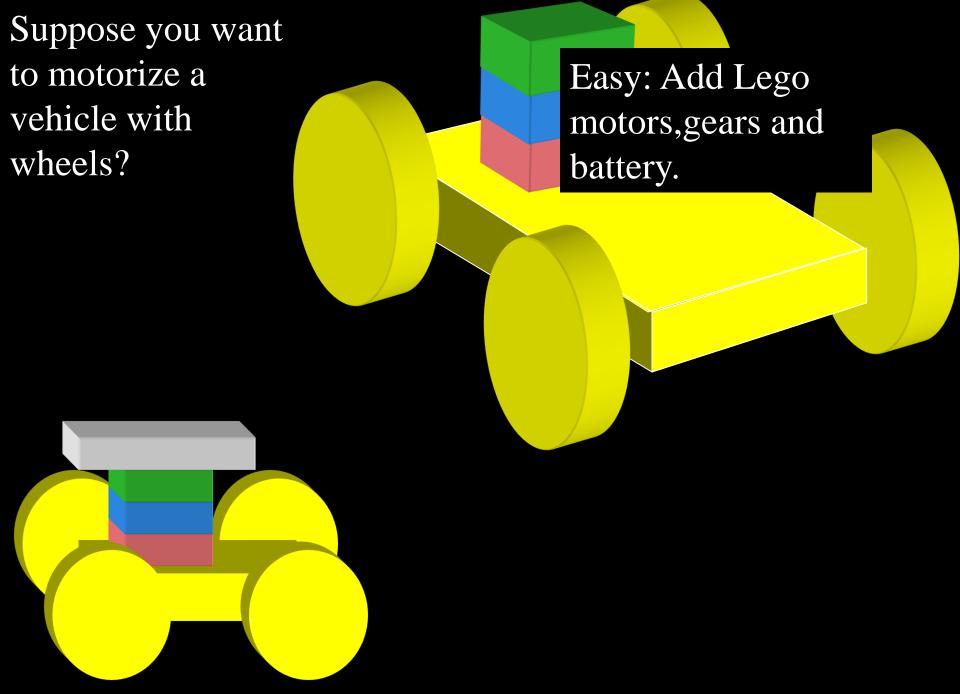






Suppose you want to put a structure on wheels?

Easy: Find Lego parts with wheels.

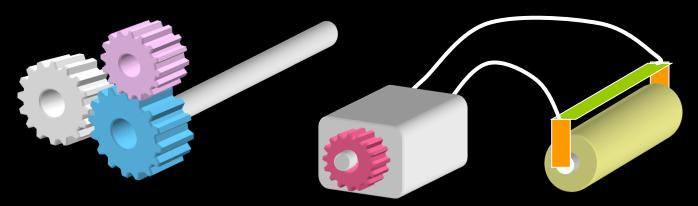


Suppose you want to motorize a vehicle with wheels?

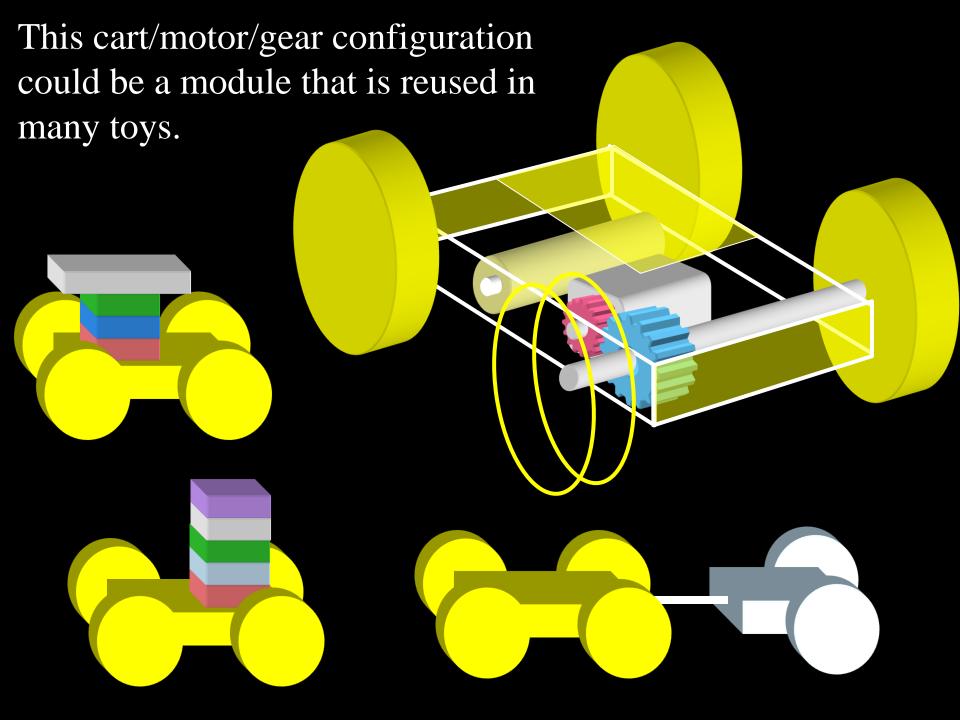
Easy: Add Lego motors, gears and battery.

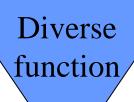
This adds additional protocols:

- Electrical protocols for batteries and motors.
- Mechanical protocols for gears and axles.



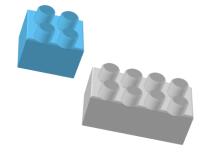
Additional protocols and modules.





# Standard assembly

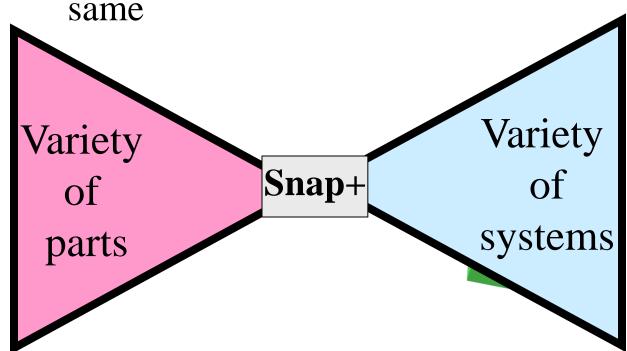
/ Diverse instructions



# **Evolvability**



- The snap/brick can be augmented with additional parts and interfaces
- Assembly remains essentially the same

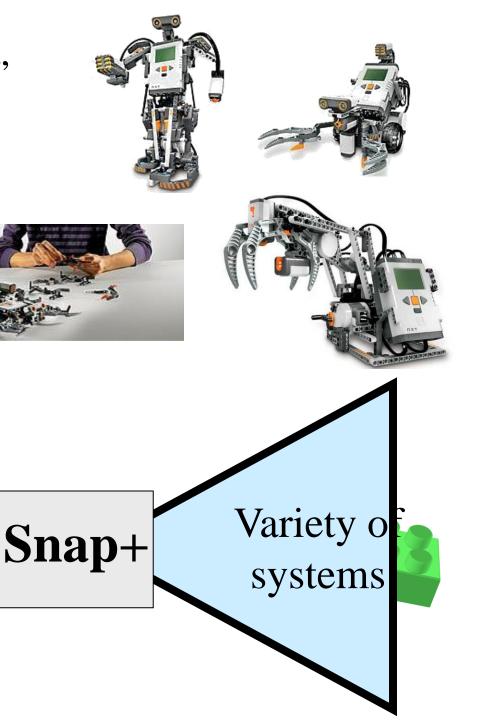


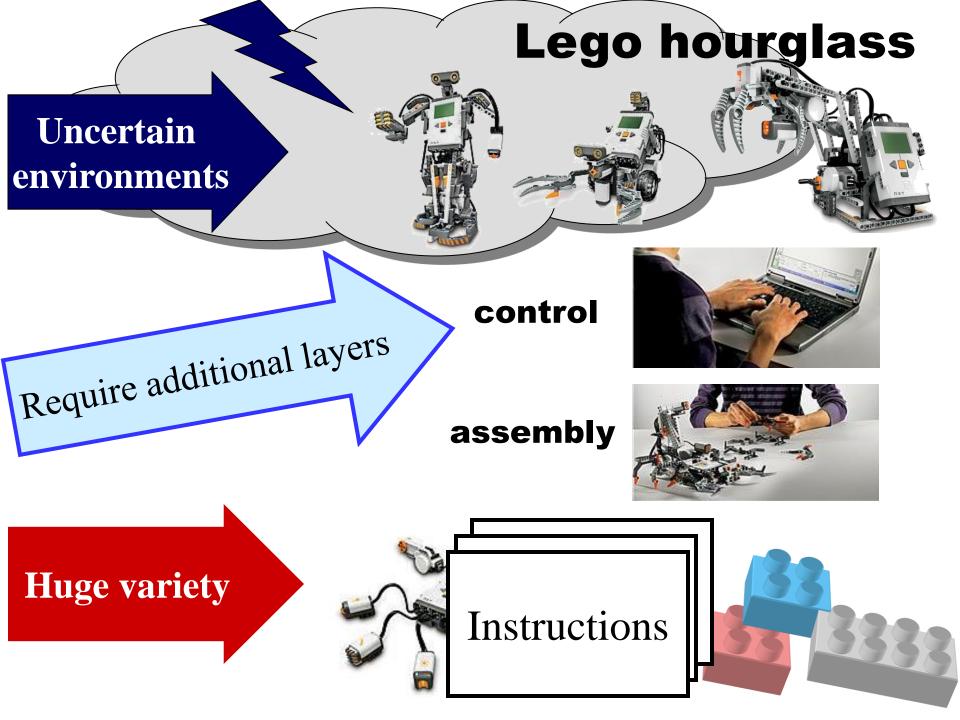
Complex toys can be created, and require additional layers of control.

education

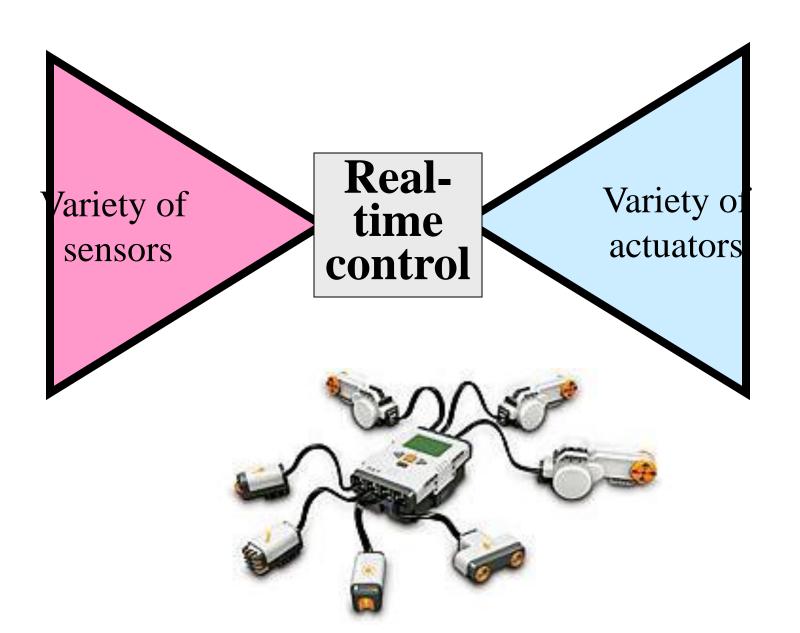
ariety of

parts

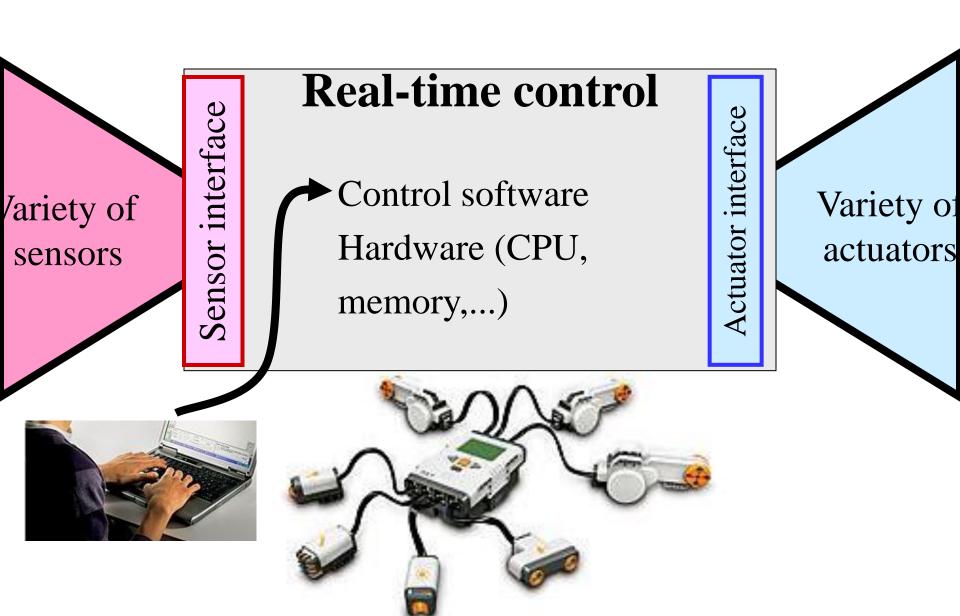


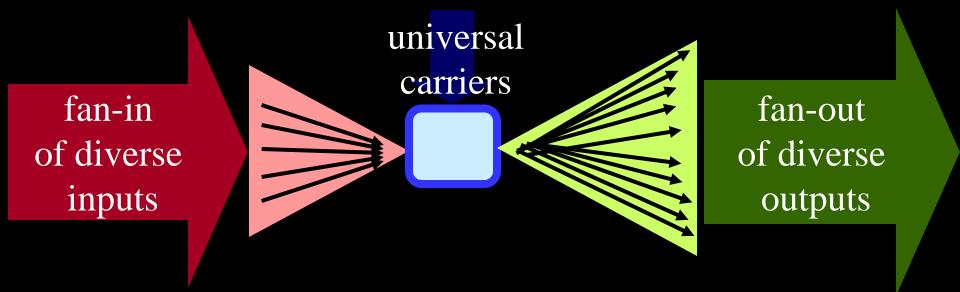


#### **NXT** controller



#### **NXT** controller



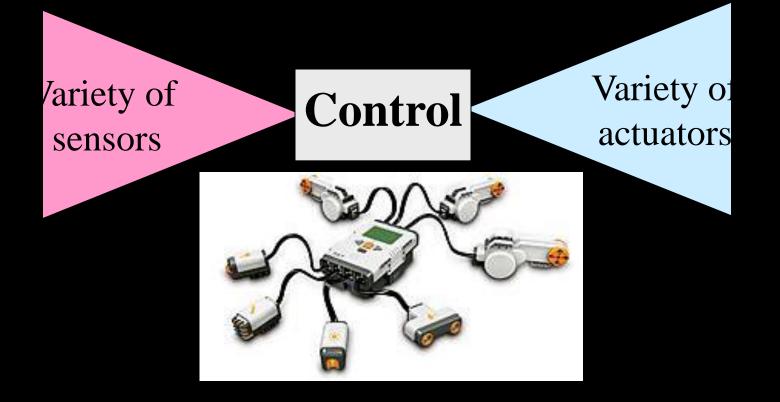


Diverse systems

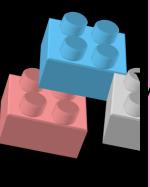
Universal Control

Diverse instructions

Bowties and Hourglasses



# Lego Bowties

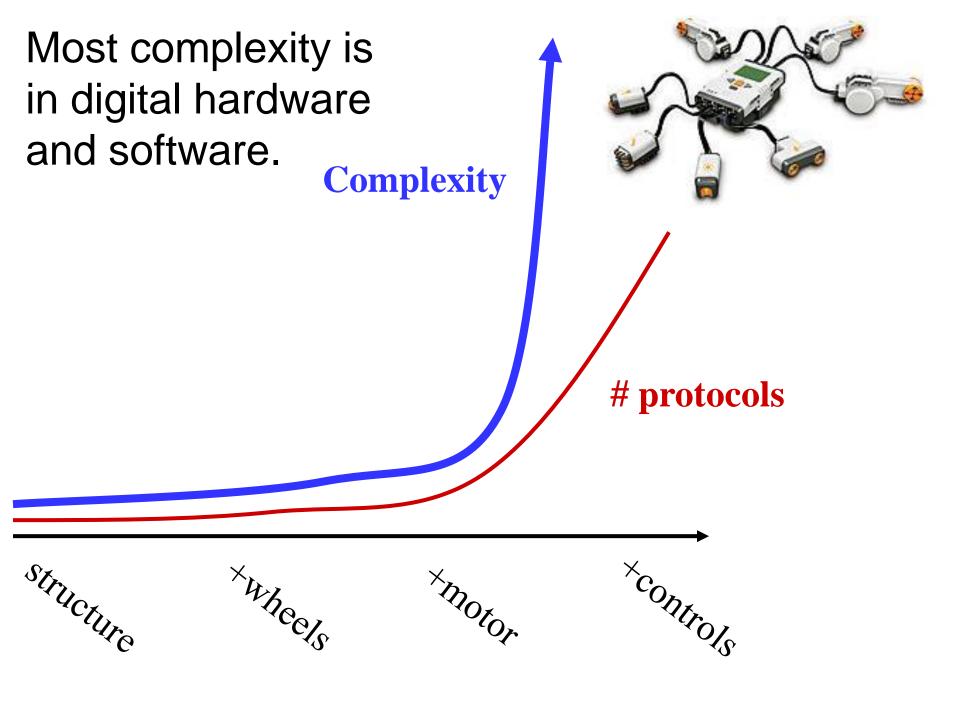


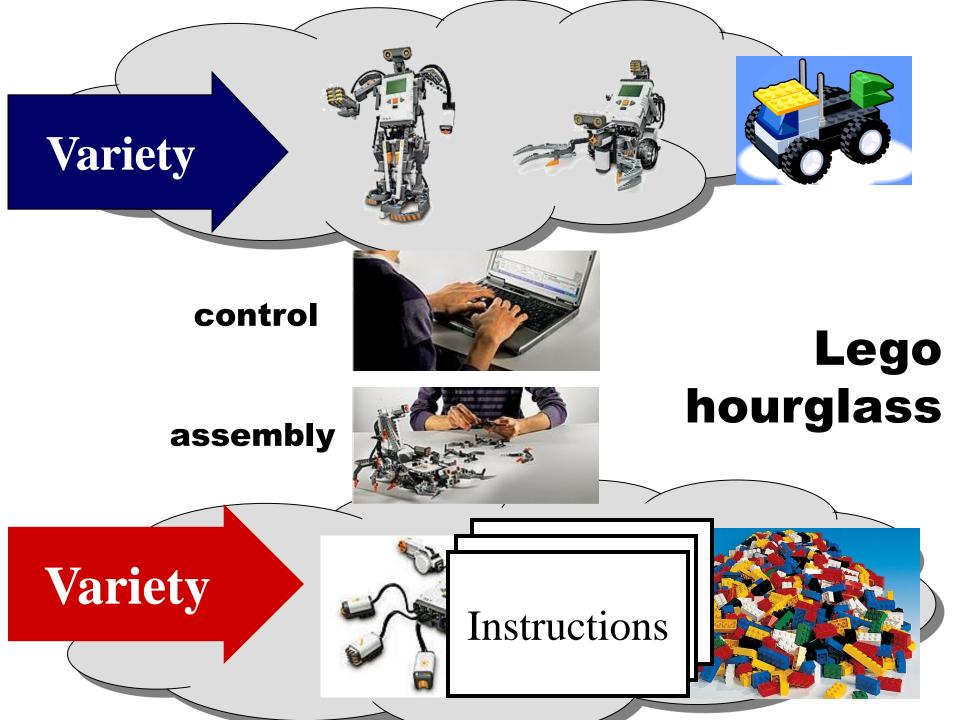
Variety of bricks

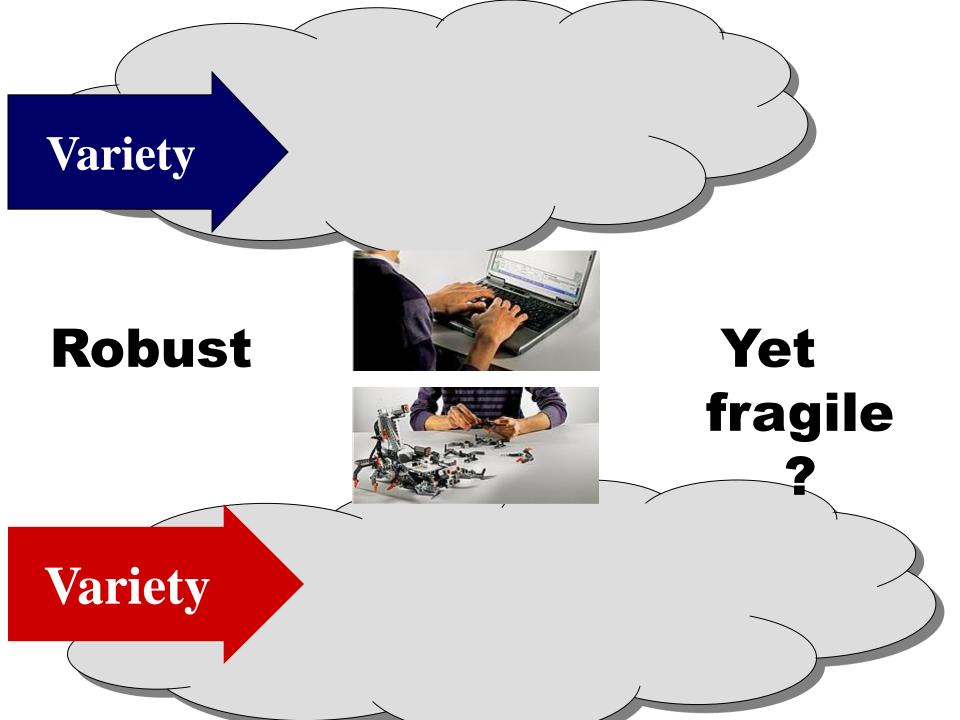
Snap

Variety of systems



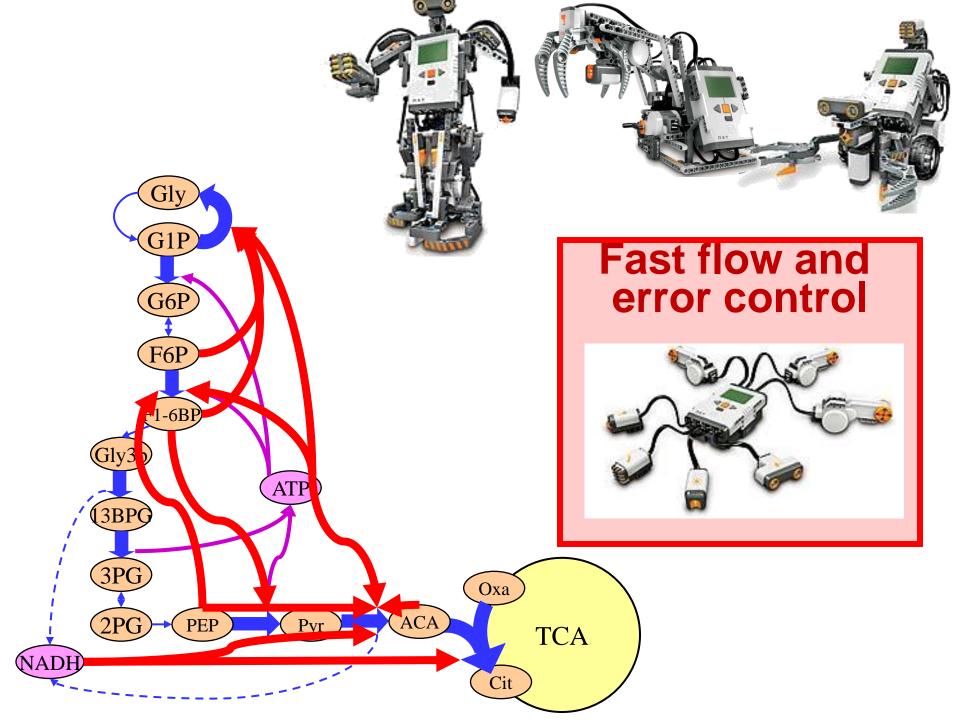


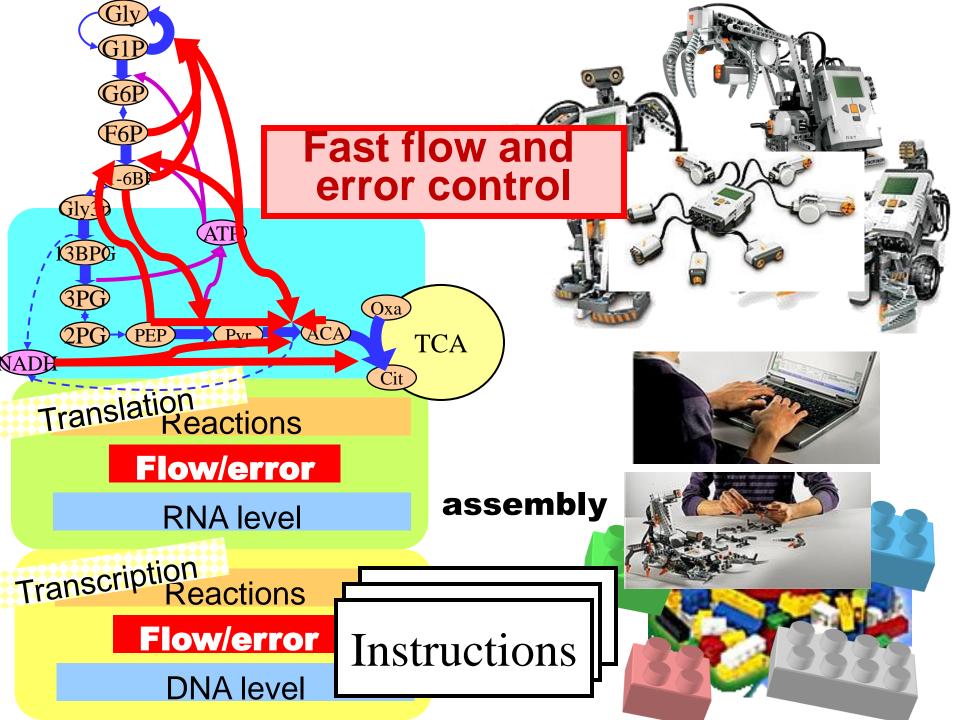












# For a single toy



### Lego hourglass

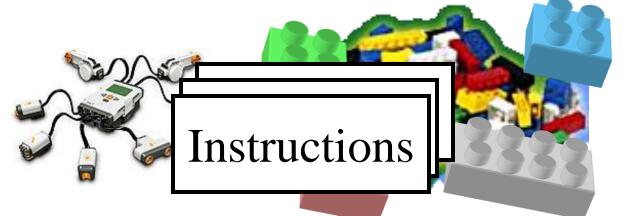


control



assembly





### Toy system

# Lego hourglass

Huge variety of toys







Standardized mechanisms
Highly conserved

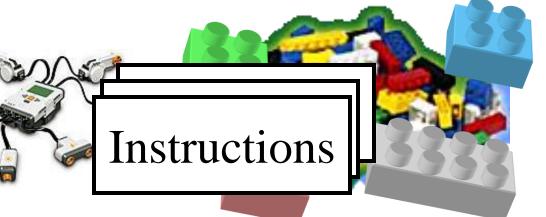
control



assembly



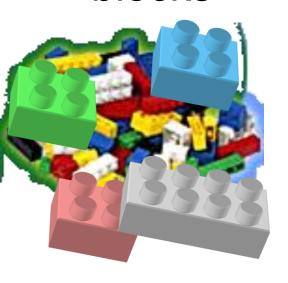
Huge variety of instructions



Building blocks

General purpose

assembly



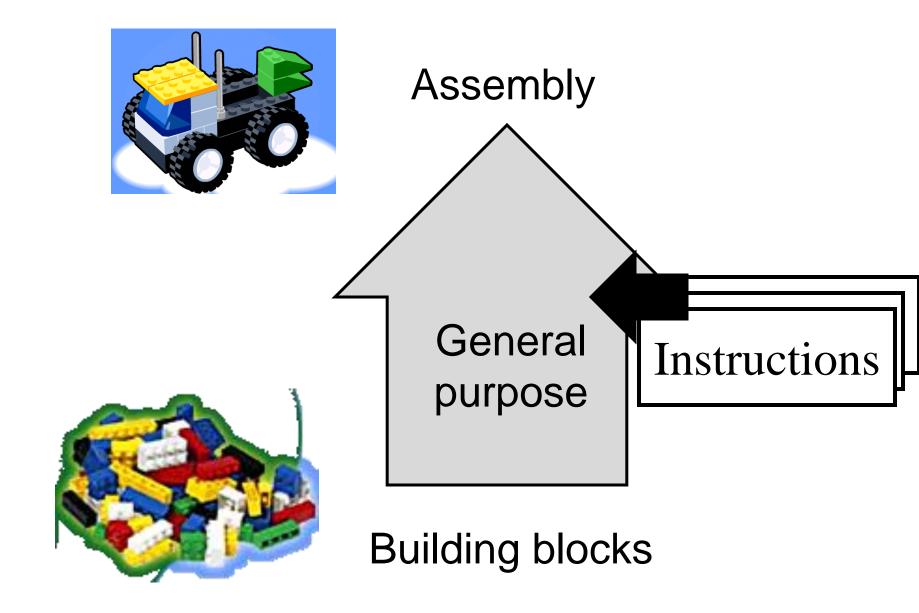




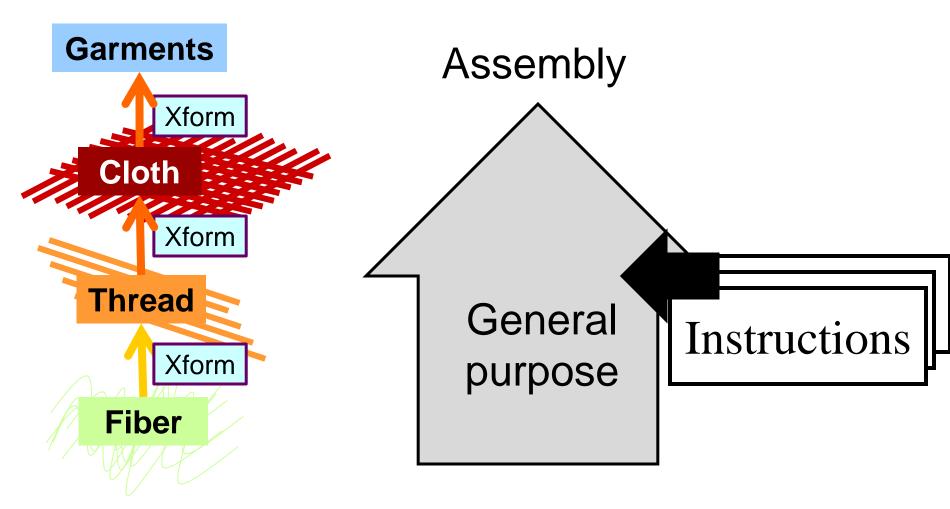
Quantized/ digital

Instructions

#### Each step uses general purpose machines

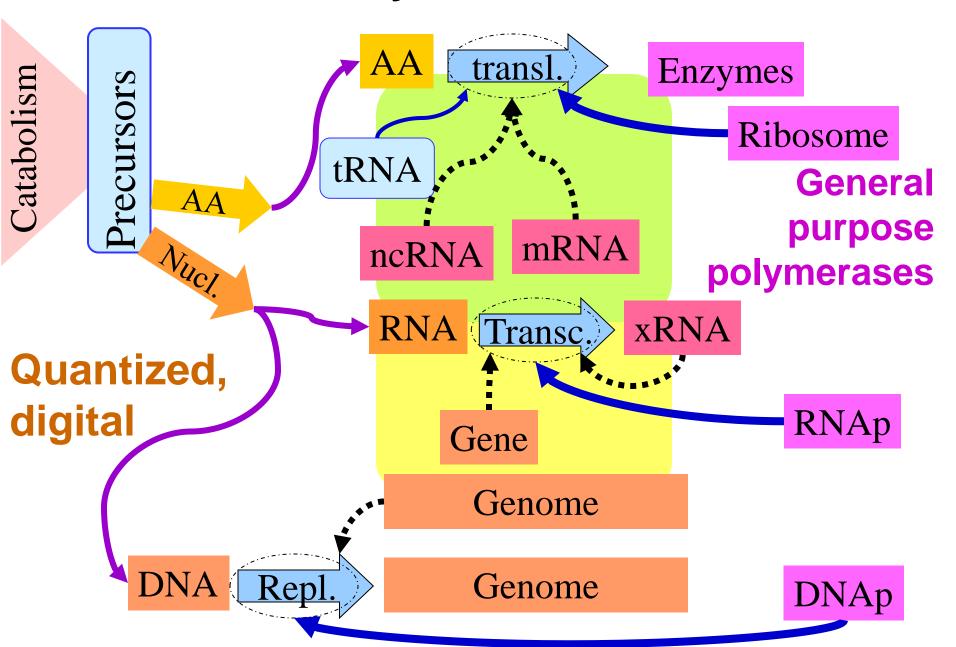


#### Each step uses general purpose machines

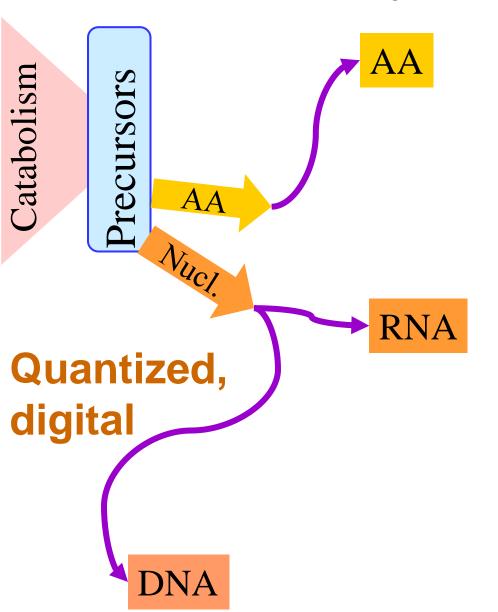


**Building blocks** 

#### **Lower layers**

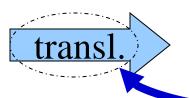


#### **Lower layers**



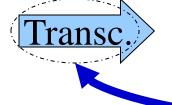
Building blocks

# Building blocks Assemblies AA Enzymes Catabolism Precursors Nucl. RNA xRNA Genome

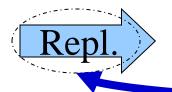


#### Ribosome

# General purpose polymerases



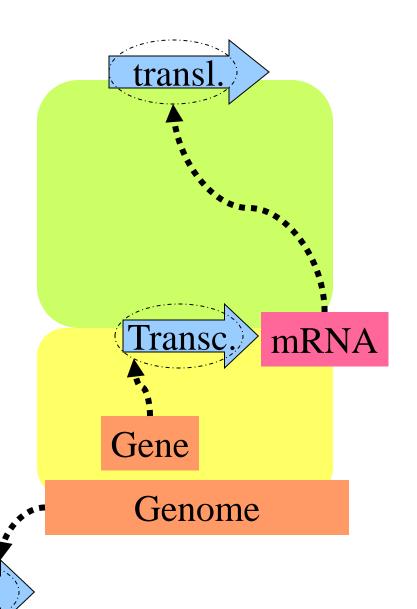
RNAp



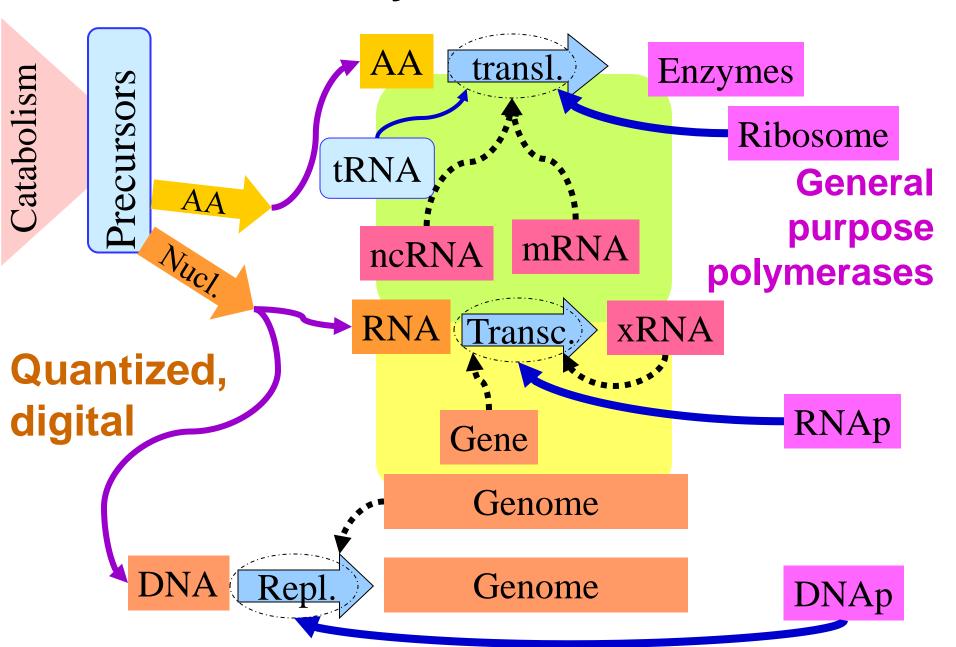
DNAp

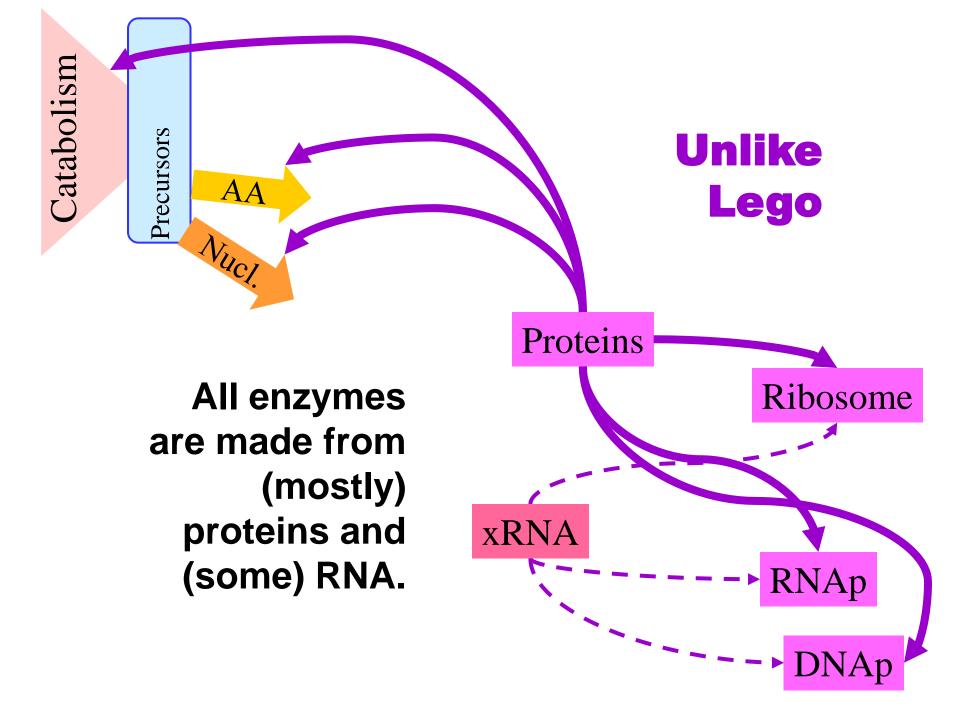
Quantized/ digital

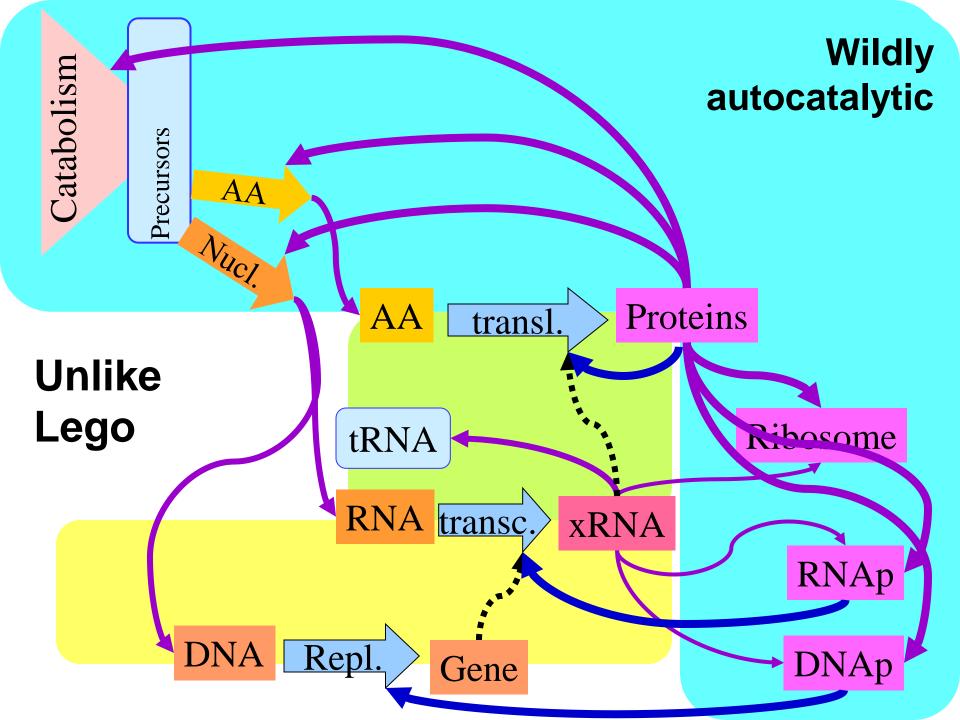
Instructions



#### **Lower layers**







# Lego hourglass

**Huge variety** of toys







control



Standardized mechanisms

Highly conserv

Arge

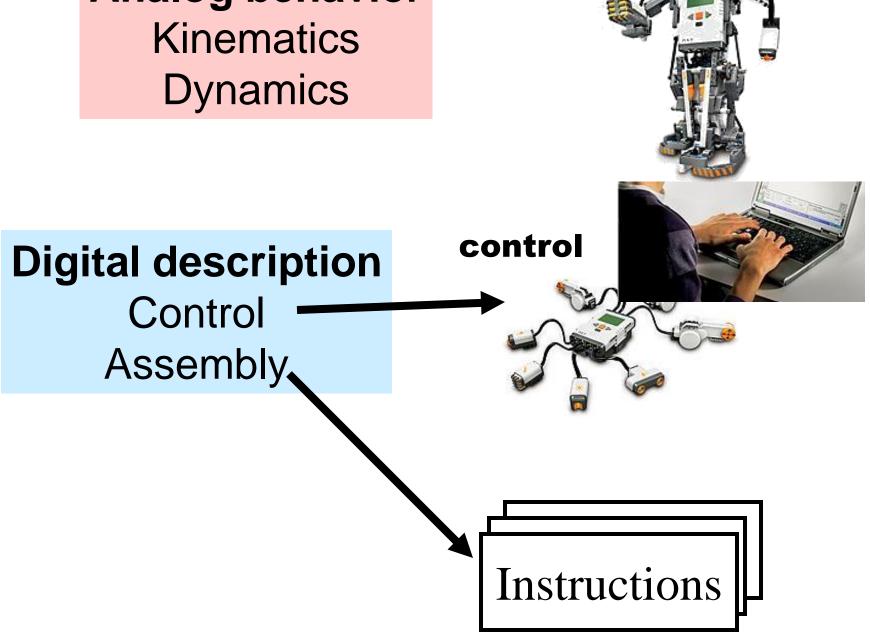
Variety of parts



of instructions



**Analog behavior Kinematics Dynamics** 



Analog behavior
Kinematics
Dynamics

control

Digital description

Control

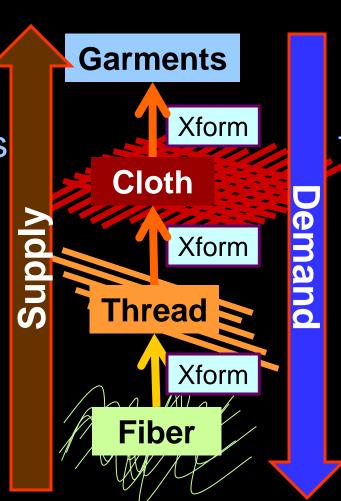
**Assembly**,

Reactions Flow/error **Carriers Proteins** Translation Reactions Flow/error **RNA** level Transcription Reactions Flow/error A level Instructions

#### **Universal strategies?**

Even though garments seem analog/continuous

quantization for robustness



Garments have limited access to threads and fibers

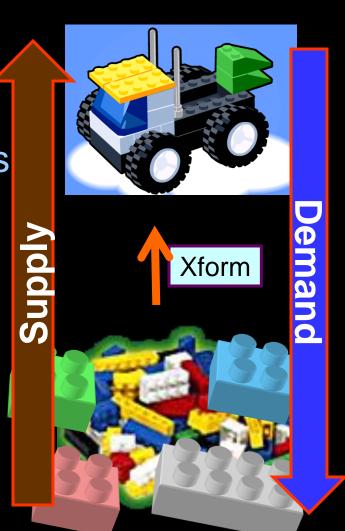
constraints on cross-layer interactions

Prevents unraveling of lower layers

### **Universal strategies?**

Even though toys seem analog/continuous

quantization for robustness



Toys have limited access to (hidden) snaps

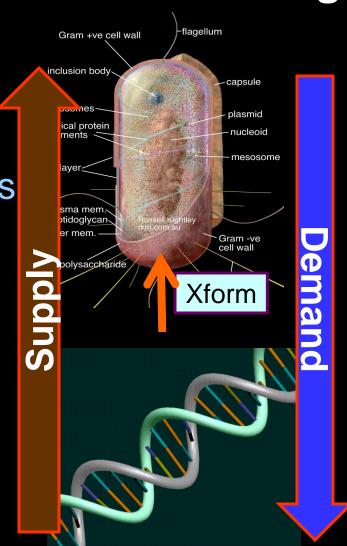
constraints on cross-layer interactions

Prevents unraveling of lower layers

### **Universal strategies?**

Even though
Cells seem
analog/continuous

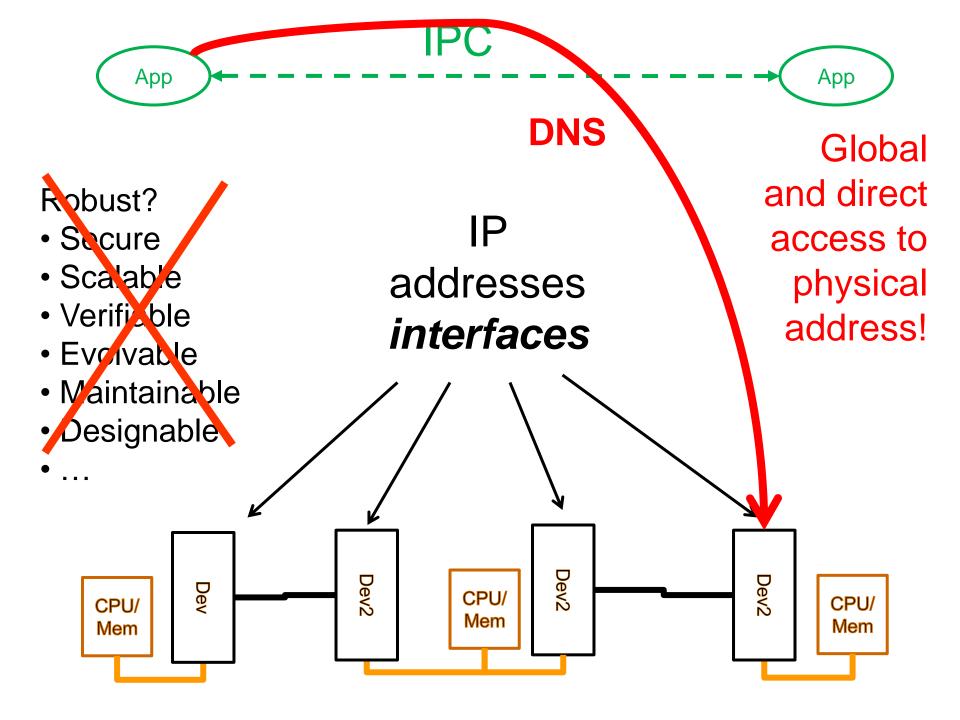
quantization for robustness

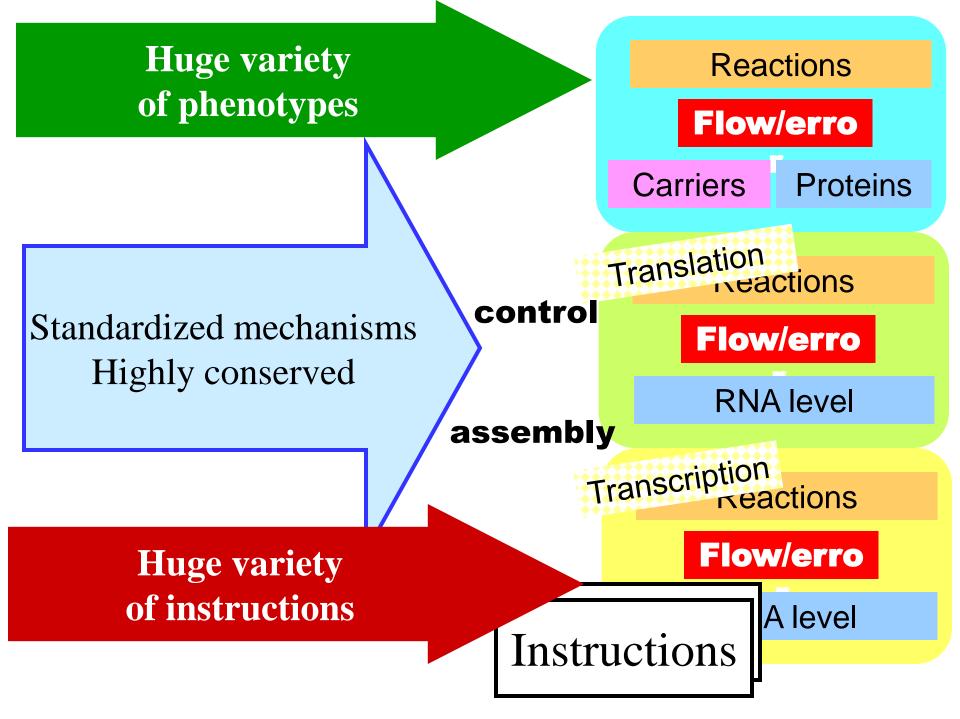


Cells have limited and structured access to DNA layer

constraints on cross-layer interactions

Prevents unraveling of lower layers





**Huge variety** of phenotypes

Reactions

Flow/erro

**Carriers** 

**Proteins** 

Standardized mechanisms Highly conserved

control

Translation Reactions

Flow/erro

**RNA** level

Large (< < huge )Variety of parts anscription Reactions

ow/erro

**Huge variety** of instructions

Instructions

A level



RNA

Frozen and evolvable

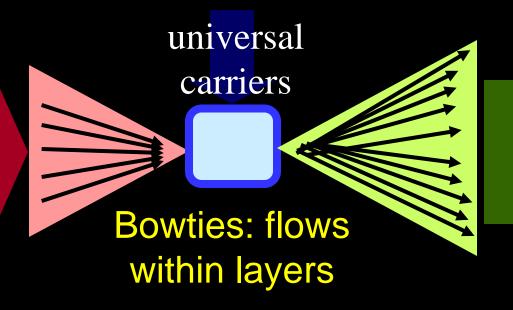
Digital and analog

Flow/erro

**DNA level** 



fan-in of diverse inputs



fan-out of diverse outputs

Diverse function

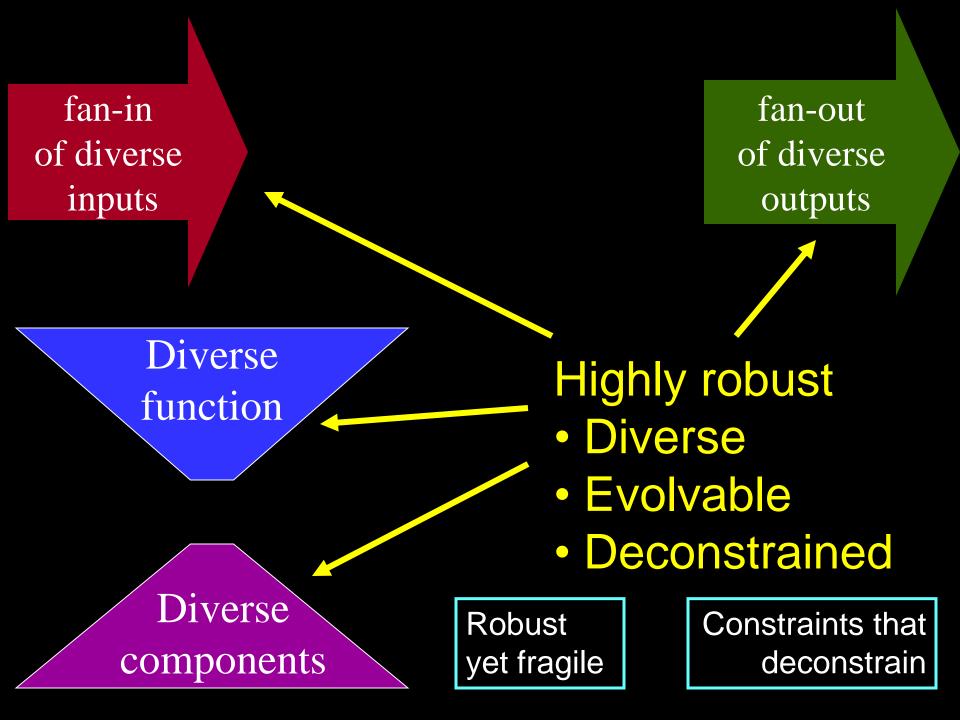
Universal Control

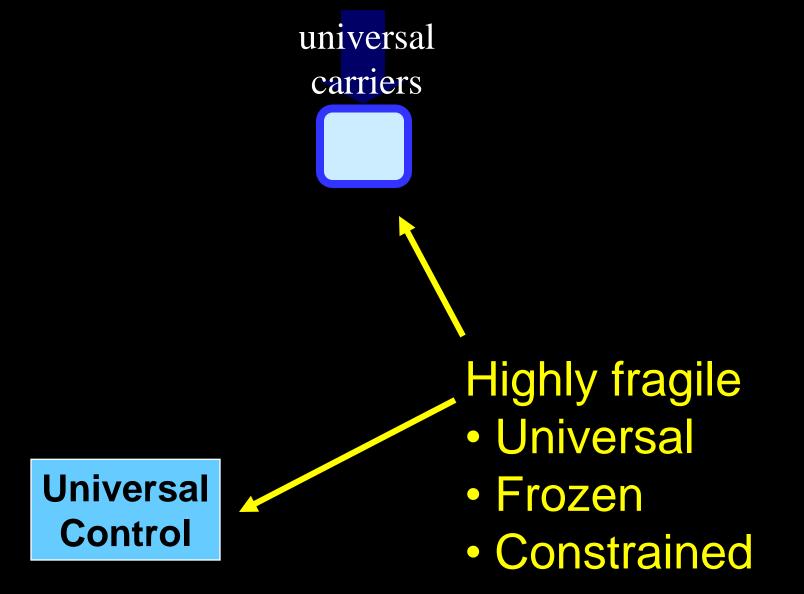
Diverse components

# **Essential ideas**

Robust yet fragile

Constraints that deconstrain

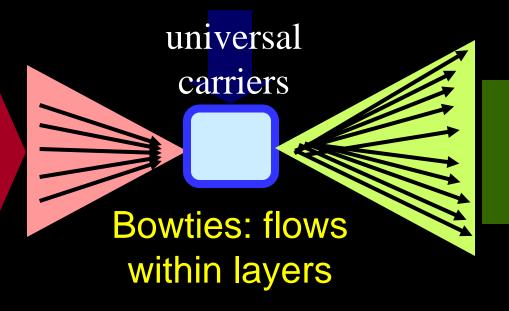




Robust yet fragile

Constraints that deconstrain

fan-in of diverse inputs



fan-out of diverse outputs

Diverse function

Universal Control

Diverse components

# **Essential ideas**

Robust yet fragile

Constraints that deconstrain

What theory is relevant to these more complex feedback systems?

$$\frac{1}{\pi} \int_{0}^{\infty} \ln |S(j\omega)| \frac{z}{z^{2} + \omega^{2}} d\omega \ge \ln \left| \frac{z + p}{z - p} \right|$$

